

# TUTORIAL NOTES FOR MATH4220

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## 1. THE MAXIMUM PRINCIPLES (HEAT EQUATION)

Recall the maximum principles.

**1.1. Notations.** Let  $\Omega \subset \mathbb{R}^n$  be a bounded domain, we set  $\Omega_T := (0, T] \times \Omega = (t, x) : 0 < t \leq T, x \in \Omega$ , we denote by  $\partial_p \Omega_T$  the parabolic boundary of  $\Omega_T$  which is defined as  $\partial_p \Omega_T := \{t = 0\} \times \bar{\Omega} \cup (0, T] \times \partial \Omega$ . As usual, we denote  $B_r$  to be the ball with radius  $r$  in  $\mathbb{R}^n$ , we set  $Q_r := (-r^2, 0] \times B_r$ . Moreover, we denote by  $C^{a,b}(\Omega_T)$  the collection of functions in  $\Omega_T$  which are  $C^a$  in  $t$  and  $C^b$  in  $x$ .

### 1.2. Theorems.

**Theorem 1** (Weak maximum principle). *Let  $\Omega \subset \mathbb{R}^n$  be a bounded domain and  $T$  be a positive constant. Let  $u \in C^{1,2}(\Omega_T) \cap C(\bar{\Omega}_T)$  with  $u_t - \Delta u \leq 0$  ( $\geq 0$ ) in  $\Omega$ . Then,*

$$\sup_{\Omega_T} u = \sup_{\partial_p \Omega_T} u \quad (\inf_{\Omega_T} u = \inf_{\partial_p \Omega_T} u).$$

Consequently, for  $u$  satisfies  $u_t - \Delta u = 0$ ,

$$\inf_{\partial_p \Omega_T} u \leq u(x) \leq \sup_{\partial_p \Omega_T} u, \quad \forall x \in \Omega.$$

**Theorem 2** (Strong maximum principle). *Let  $\Omega \subset \mathbb{R}^n$  be a bounded domain and  $T$  be a positive constant. Let  $u \in C^{1,2}(\Omega_T) \cap C(\bar{\Omega}_T)$  with  $u_t - \Delta u \leq 0$  ( $\geq 0$ ) in  $\Omega$ , and suppose there exists a point  $(\tau, y) \in \Omega_T$  for which  $u(\tau, y) = \sup_{\Omega_T} u$  ( $\inf_{\Omega_T} u$ ). Then  $u \equiv u(\tau, y)$  is constant in  $(0, \tau) \times \Omega$ . Consequently the solution to heat equation cannot assume an interior maximum or minimum value unless it is constant.*

**1.3. Applications.** Let us show some results given by the mean value theorems and the maximum principles.

**Example 3** (Interior gradient estimates). Suppose  $u \in C^{1,2}(Q_1) \cap C(\bar{Q}_1)$  satisfies

$$u_t - \Delta u = 0 \quad \text{in } Q_1.$$

Then there holds

$$\sup_{Q_{\frac{1}{2}}} |Du| \leq c \sup_{\partial_p Q_1} |u|,$$

where  $c = c(n)$  is a positive constant. In particular for any  $\alpha \in [0, 1]$  there holds

$$|u(t, x) - u(t, y)| \leq c|x - y|^\alpha \sup_{\partial_p Q_1} |u|, \quad \forall t > 0, x, y \in B_{\frac{1}{2}},$$

where  $c = c(n, \alpha)$  is a positive constant.

*Proof.* Direct computation shows that

$$(\partial_t - \Delta)(|Du|^2) = -2 \sum_{i,j=1}^n (D_{ij}u)^2 + 2 \sum_{i=1}^n D_i u D_i (\partial_t u - \Delta u) = -2 \sum_{i,j=1}^n (D_{ij}u)^2,$$

moreover,

$$(\partial_t - \Delta)(\varphi |Du|^2) = (\partial_t \varphi - \Delta \varphi) |Du|^2 - 4 \sum_{i,j=1}^n D_i \varphi D_j u D_{ij} u - 2\varphi \sum_{i,j=1}^n (D_{ij}u)^2, \quad \forall \varphi \in C_0^1(B_1).$$

By taking  $\varphi = \eta^2$  for some  $\eta \in C_0^1(B_1)$  with  $\eta \equiv 1$  in  $B_{\frac{1}{2}}$ , we obtain by the Hölder's inequality,

$$\begin{aligned} (\partial_t - \Delta)(\eta^2 |Du|^2) &= (2\eta \partial_t \eta - 2\eta \Delta \eta - 2|D\eta|^2) |Du|^2 \\ &\quad - 8\eta \sum_{i,j=1}^n D_i \eta D_j u D_{ij} u - 2\eta^2 \sum_{i,j=1}^n (D_{ij}u)^2 \\ &\leq (2\eta \partial_t \eta - 2\eta \Delta \eta + 6|D\eta|^2) |Du|^2 \leq C |Du|^2, \end{aligned}$$

where  $C$  is a positive constant depending only on  $\eta$ . Moreover, since

$$(\partial_t - \Delta)(u^2) = -2|Du|^2 + 2u(\partial_t u - \Delta u) = -2|Du|^2,$$

by choosing  $\alpha$  large enough we get

$$\Delta(\eta^2 |Du|^2 + \alpha u^2) \leq 0,$$

then by the maximum principle, we have

$$\sup_{Q_1} (\eta^2 |Du|^2 + \alpha u^2) \leq \sup_{\partial_p Q_1} (\eta^2 |Du|^2 + \alpha u^2),$$

which implies

$$\sup_{Q_{\frac{1}{2}}} |Du| \leq c \sup_{\partial_p Q_1} |u|,$$

where  $c = c(n)$  is a positive constant. Therefore we have

$$|u(t, x) - u(t, y)| \leq c |x - y|^\alpha \sup_{\partial_p Q_1} |u|, \quad \forall t > 0, x, y \in B_{\frac{1}{2}}.$$

□

**Example 4** (Li-Yau estimate). Suppose  $u$  is a non-negative function satisfies

$$\partial_t u - \Delta u = 0 \quad \text{in } (0, T] \times \mathbb{R}^n.$$

Then there holds

$$\frac{|Du|^2}{u^2} - \frac{\partial_t u}{u} \leq \frac{n}{2t},$$

In particular, for arbitrary  $(t_1, x_1), (t_2, x_2) \in (0, T] \times \mathbb{R}^n$  with  $t_2 > t_1 > 0$ , there holds

$$\frac{u(t_1, x_1)}{u(t_2, x_2)} \leq \left( \frac{t_2}{t_1} \right)^{\frac{n}{2}} e^{\frac{|x_2 - x_1|^2}{4(t_2 - t_1)}}.$$

*Proof.* We divide the proof into several steps.

Firstly, we derive some equations involving  $v = \log u$ . For  $v$ , we have

$$\partial_t v - \Delta v = |Dv|^2,$$

moreover, denote  $w = |Dv|^2$ , then

$$\partial_t w - \Delta w = 2Dv \cdot Dw - 2 \sum_{i,j=1}^n (D_{ij}v)^2.$$

Secondly, for  $\alpha \in (0, 1)$ , set  $f = \alpha|Dv|^2 - v_t$ , then

$$\partial_t f - \Delta f = 2Dv \cdot Df - 2\alpha \sum_{i,j=1}^n (D_{ij}v)^2.$$

Since

$$\begin{aligned} \sum_{i,j=1}^n (D_{ij}v)^2 &\geq \frac{1}{n}(\Delta v)^2 = \frac{1}{n}(|Dv|^2 - v_t) = \frac{1}{n}((1-\alpha)|Dv|^2 + f)^2 \\ &\geq \frac{1}{n}(f^2 + 2(1-\alpha)|Dv|^2 f + (1-\alpha)^2|Dv|^4) \\ &\geq \frac{1}{n}(f^2 + 2(1-\alpha)|Dv|^2 f), \end{aligned}$$

therefore

$$\partial_t f - \Delta f \leq 2Dv \cdot Df - \frac{2\alpha}{n}(f^2 + 2(1-\alpha)|Dv|^2 f).$$

Thirdly, for arbitrary  $\varphi \in C_0^\infty(\mathbb{R}^n)$  with  $\varphi \geq 0$ , let  $g = t\varphi f$ , we have

$$\begin{aligned} t\varphi \partial_t f &= g_t - \frac{g}{t}, \\ t\varphi Df &= Dg - \frac{D\varphi}{\varphi}g, \\ t\varphi \Delta f &= \Delta g - 2\frac{D\varphi}{\varphi} \cdot Dg + \left(2\frac{|D\varphi|^2}{\varphi^2} - \frac{\Delta\varphi}{\varphi}\right)g. \end{aligned}$$

Therefore substituting  $\partial_t f$ ,  $Df$ ,  $\Delta f$  by the above relations, we obtain

$$\begin{aligned} &t\varphi(\partial_t g - \Delta g) + t(D\varphi - \varphi Dv) \cdot Dg \\ &\leq g \left[ \varphi - \frac{2\alpha}{n}g + t \left( 2\frac{|D\varphi|^2}{\varphi} - \Delta\varphi + \frac{n}{4\alpha(1-\alpha)} \frac{|D\varphi|^2}{\varphi} \right) \right]. \end{aligned}$$

By letting  $\varphi = \eta^2$  for  $\eta \in C_0^\infty(\mathbb{R}^n)$  with  $\eta \geq 0$ , we get

$$\begin{aligned} &t\eta^2(\partial_t g - \Delta g) + t(2\eta D\eta - \eta^2 Dv) \cdot Dg \\ &\leq g \left[ \eta^2 - \frac{2\alpha}{n}g + t \left( 6|D\eta|^2 - 2\eta\Delta\eta + \frac{n}{\alpha(1-\alpha)}|D\eta|^2 \right) \right]. \end{aligned}$$

Let  $\eta_0$  be a cutoff function with  $0 \leq \eta_0 \leq 1$  in  $B_1$  and  $\eta_0 \equiv 1$  in  $B_{\frac{1}{2}}$ , then let  $\eta(x) = \eta_0(\frac{x}{R})$ , we have

$$t\eta^2(\partial_t g - \Delta g) + t(2\eta D\eta - \eta^2 Dv) \cdot Dg \leq g \left( 1 - \frac{2\alpha}{n}g + \frac{C_\alpha t}{R^2} \right).$$

We claim that

$$(1.1) \quad 1 - \frac{2\alpha}{n}g + \frac{C_\alpha t}{R^2} \geq 0 \quad \text{in } (0, T] \times B_R.$$

Denote  $h := 1 - \frac{2\alpha}{n}g + \frac{C_\alpha t}{R^2}$ , suppose to the contrary, that  $h$  has a negative minimum at  $(t_0, x_0) \in Q_T$ , then  $h(t_0, x_0) < 0$ ,  $\partial_t h(t_0, x_0) \leq 0$ ,  $Dh(t_0, x_0) = 0$ , and

$\Delta h(t_0, x_0) \geq 0$ , therefore  $g(t_0, x_0) > 0$ ,  $\partial_t g(t_0, x_0) \geq 0$ ,  $Dg(t_0, x_0) = 0$ , and  $\Delta g(t_0, x_0) \leq 0$ . Then on the one hand, at  $(t_0, x_0)$ , we have

$$t\eta^2(\partial_t g - \Delta g) + t(2\eta D\eta - \eta^2 Dv) \cdot Dg \geq 0,$$

on the other hand, we also have

$$t\eta^2(\partial_t g - \Delta g) + t(2\eta D\eta - \eta^2 Dv) \cdot Dg \leq g \left( 1 - \frac{2\alpha}{n}g + \frac{C_\alpha t}{R^2} \right) < 0,$$

which is a contradiction. Let  $R$  goes to infinity in (1.1), we have

$$\frac{|Du|^2}{u^2} - \frac{\partial_t u}{u} \leq \frac{n}{2t}.$$

Finally, to prove the Harnack inequality, for  $(t_1, x_1), (t_2, x_2) \in (0, T] \times \mathbb{R}^n$ , take an arbitrary path  $x(t)$  for  $t \in [t_1, t_2]$  with  $x(t_1) = x_1, x(t_2) = x_2$ , then

$$\begin{aligned} \frac{dv(t, x(t))}{dt} &= v_t + Dv \cdot \frac{dx(t)}{dt} \\ &\geq |Dv|^2 + Dv \cdot \frac{dx(t)}{dt} - \frac{n}{2t} \\ &\geq -\frac{1}{4} \left| \frac{dx(t)}{dt} \right|^2 - \frac{n}{2t}. \end{aligned}$$

then

$$v(t_1, x_1) \leq v(t_2, x_2) + \frac{n}{2} \log \frac{t_2}{t_1} + \frac{1}{4} \int_{t_1}^{t_2} \left| \frac{dx(t)}{dt} \right|^2 dt.$$

Let  $x(t) = at + b$ , where

$$a = \frac{x_2 - x_1}{t_2 - t_1}, \quad b = \frac{t_2 x_1 - t_1 x_2}{t_2 - t_1}.$$

Then

$$v(t_1, x_1) \leq v(t_2, x_2) + \frac{n}{2} \log \frac{t_2}{t_1} + \frac{1}{4} \frac{|x_2 - x_1|^2}{t_2 - t_1},$$

therefore

$$\frac{u(t_1, x_1)}{u(t_2, x_2)} \leq \left( \frac{t_2}{t_1} \right)^{\frac{n}{2}} e^{\frac{|x_2 - x_1|^2}{4(t_2 - t_1)}}.$$

□

### A Supplementary Problem

For a bounded region  $\Omega \subset \mathbb{R}^n$  and a positive constant  $T$ , if  $u$  satisfies

$$\begin{aligned} \partial_t u - \Delta u &= f, & \text{in } \Omega_T, \\ u(0, \cdot) &= u_0, & \text{on } \Omega, \\ u &= \varphi, & \text{on } (0, T) \times \partial\Omega. \end{aligned}$$

Show that

$$\sup_{\Omega_T} |u| \leq C \left( \sup_{\Omega} |u_0| + \sup_{[0, T] \times \partial\Omega} |\varphi| + \sup_{\Omega_T} |f| \right),$$

where  $C = C(T, \Omega)$  is a positive constant.

For more materials, please refer to [1, 2, 3, 4].

## REFERENCES

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